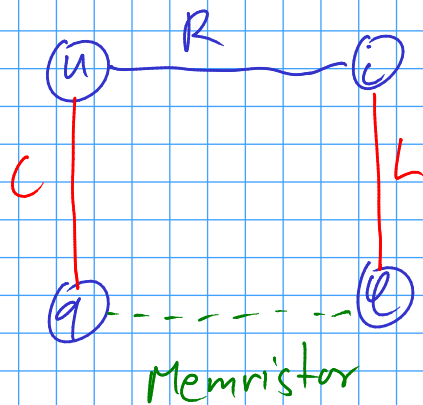
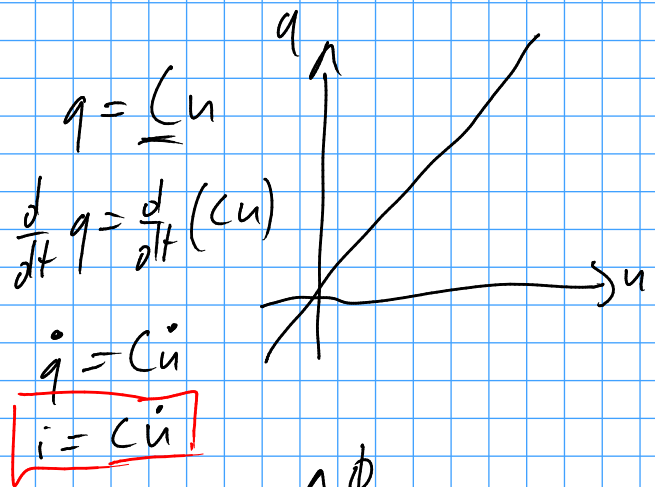
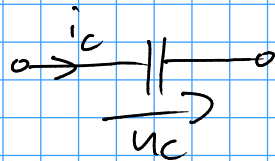


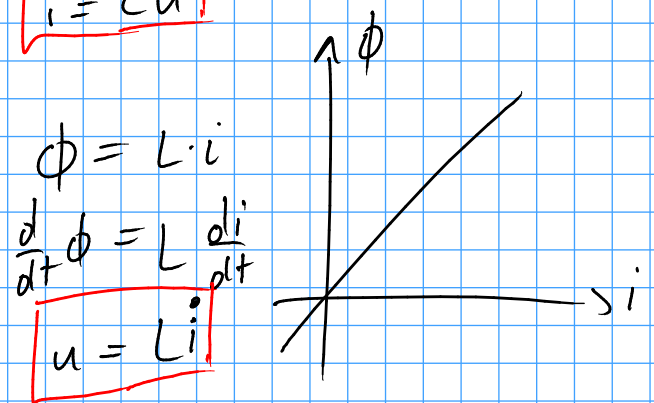
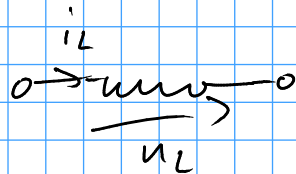
⇒ Einführung reaktive Bauelemente



• Kapazität



• Induktivität

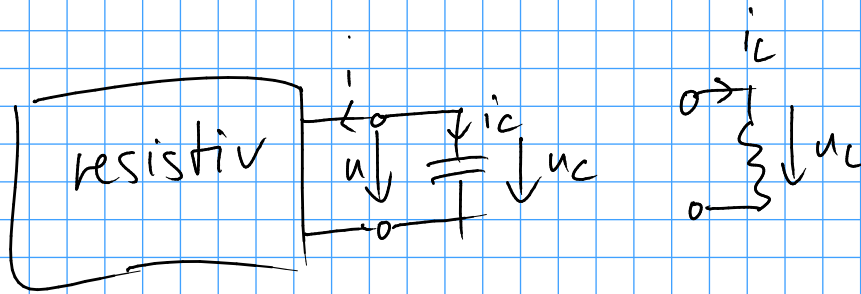


Lineare Schaltung 1. Grades

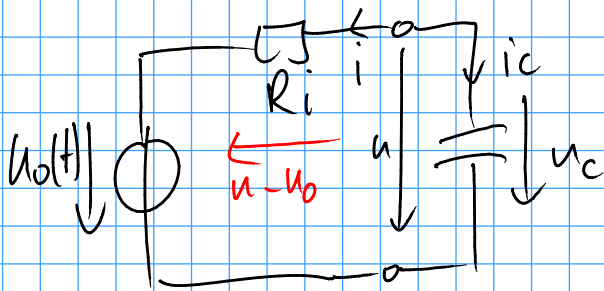
① Zustandsgröße festlegen
 ↳ stetig

$C \rightarrow u$
 $L \rightarrow i$

② alle übrigen resistiven Bauelemente werden zusammengefasst

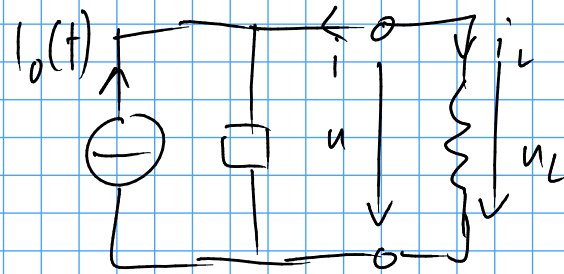


Helmholtz/Thévenin



$C \rightarrow U$

Norton/Walton



$L \rightarrow KS$

→ Parameter (U_0, R_i) bzw. (I_0, G) berechnen

③ Zustandsgleichung aufstellen

Bsp: $i_c = C \dot{u}_c \Leftrightarrow \dot{u}_c = \frac{i_c}{C}$ Ziel $\dot{u}_c = f(u_c)$

$$= -\frac{i}{C} = -\frac{u - U_0}{RC} = -\frac{u_c - U_0}{RC}$$

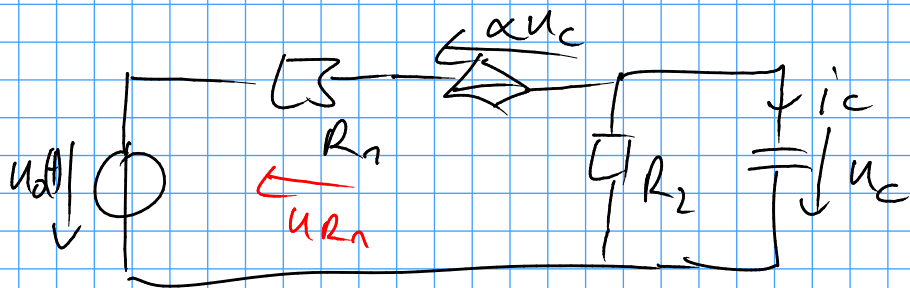
$$\dot{u}_c = -\frac{u_c}{RC} + \frac{U_0}{RC} \quad \tau = RC$$

$$\tau = GL$$

$$\dot{x}(t) = -x(t) \cdot \frac{1}{\tau} + x(t_\infty) \cdot \frac{1}{\tau}$$

$$\Rightarrow x(t) = x(t_\infty) + [x(t_0) - x(t_\infty)] e^{-\frac{t-t_0}{\tau}}$$

ST 2 - Blatt 1



2. $\dot{u}_c = \frac{1}{C} i_c$ mit $i_c + \frac{u_c}{R_2} + \frac{u_{R_1}}{R_1} = 0$

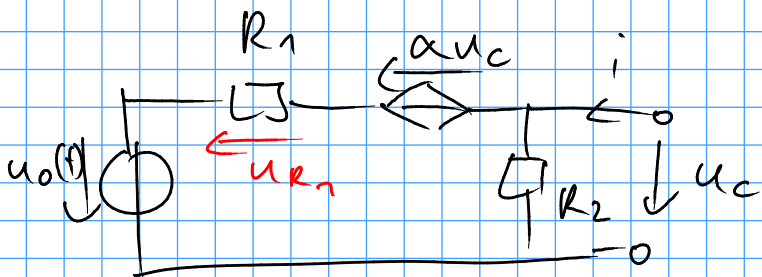
$$u_{R_1} = -\alpha u_c + u_c - u_0(t)$$

$$i_c = -\frac{u_c}{R_2} - \frac{u_{R_1}}{R_1} = -\frac{u_c}{R_2} - \frac{-\alpha u_c + u_c - u_0(t)}{R_1}$$

$$= -u_c \left(\frac{1}{R_2} + \frac{1}{R_1} (1 - \alpha) \right) + \frac{u_0(t)}{R_1}$$

$$\Rightarrow \dot{u}_c = \frac{1}{C} u_c \left(\frac{1}{R_2} + \frac{1}{R_1} (\alpha - 1) \right) + \frac{u_0(t)}{R_1 C}$$

Alternative über ECB: Betrachtung des Falls $\dot{u}_c = 0 = i_c$



$$R = \frac{u_c}{i} \Big|_{u_0(t)=0}$$

$$i = \frac{u_c}{R_2} + \frac{u_{R_1}}{R_1} = \frac{u_c}{R_2} + \frac{u_c(1-\alpha)}{R_1}$$

$$u_{R_1} = -\alpha u_c + u_c = u_c(1-\alpha)$$

$$R = \frac{u_c}{u_c \left(\frac{1}{R_2} + \frac{1-\alpha}{R_1} \right)} = \frac{1}{\frac{1}{R_2} + \frac{1-\alpha}{R_1}}$$

$$\tilde{u}_o(t) = u_c \Big|_{i=0}$$

$$u_c = \alpha u_c - \frac{u_c}{R_2} \cdot R_1 + u_o(t)$$

$$u_c \left(1 - \alpha + \frac{R_1}{R_2} \right) = u_o(t)$$

$$= \frac{u_o(t)}{1 - \alpha + \frac{R_1}{R_2}}$$

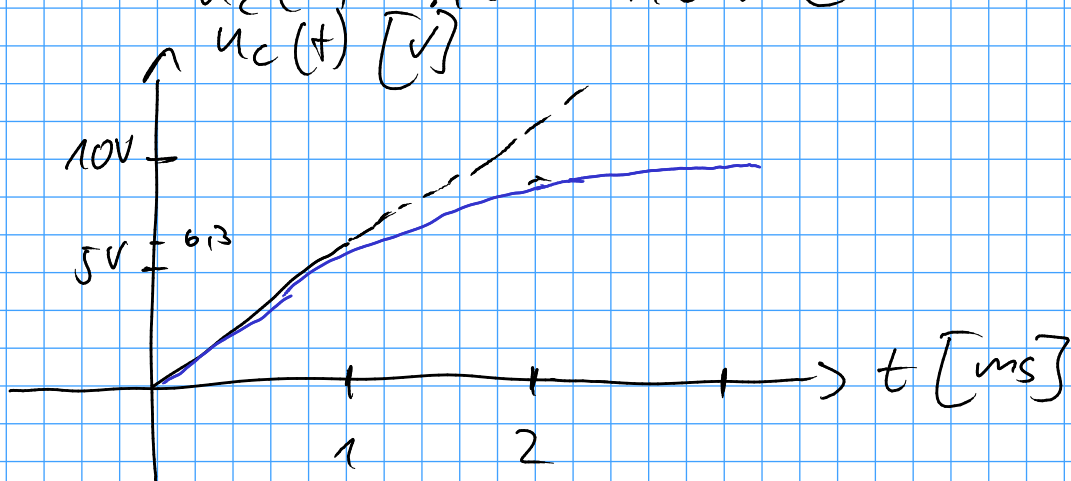
3. $\alpha = 1 \Rightarrow \tilde{u}_o(t) = \frac{10V}{1} = 10V$

$$R = 1k\Omega$$

$$\tau = RC = 1k\Omega \cdot 1\mu F = 1ms$$

allg. Lösung: $x(t) = x(t_0) + [x(t_0) - x(t_0)] e^{-\frac{t-t_0}{\tau}}$

ALSO: $u_c(t) = 10V - 10V e^{-\frac{t}{1ms}}$



$$u_c(2ms) = 10V - 10V e^{-2} = 10V - 1.4V = 8.6$$

$$4. \quad \alpha = 3$$

$$\tilde{u}_0(t) = \frac{-10V}{1-3+1} = 10V$$

$$R = \frac{1}{\frac{1}{1k\Omega} - \frac{2}{1k\Omega}} = -1k\Omega$$

$$u_c(t) = 10V + [8,6V - 10V] e^{\frac{t-2ms}{1ms}}$$
$$= 10V - 1,4V e^{\frac{t-2ms}{1ms}}$$

↳ instabil

$$u_c(t) \stackrel{!}{=} 0 \Leftrightarrow 10V - 1,4V e^{\frac{t-2ms}{1ms}} = 0$$

$$e^{\frac{t-2ms}{1ms}} = \frac{10}{1,4} = 7,14$$

(ln)

$$\frac{t-2ms}{1ms} = 2$$
$$t = 4ms$$